

EX three

1. Can A2 execute before B1?

Reasoning:

- Initially: $start = 0, done = 0, 11$
- For A to reach A2, it must pass $P(done)$, so $done$ must be 1 at that moment.
- $done$ can only become 1 by $V(done)$ in process B, which is executed **after** B1.
- Therefore, A2 cannot start before B1 has finished, because it is blocked on $P(done)$ until B executes $V(done)$ following B1.

So **no execution** allows A2 before B1; the semaphore $done$ enforces $B1 \rightarrow A2$.

2. If $V(start)$ is moved after A2

New (incorrect) code:

Process A:	Process B:
A1;	$P(start)$;
$P(done)$;	B1;
A2;	$V(done)$;
$V(start)$;	

Execution:

- Initially: $start = 0, done = 0$.
- Suppose A runs first. A1 executes, then A executes $P(done)$ and blocks because $done = 0$.
- B cannot start B1 because it is blocked on $P(start)$ and $start = 0$.
- A will never execute $V(start)$ (it is after A2, and A is blocked before A2).
- B will never execute $V(done)$ (it is after B1, and B is blocked before B1).

Both processes are blocked forever: **deadlock** occurs. The required order $A1 \rightarrow B1 \rightarrow A2$ is also violated because the program never progresses.

3. Generalization to 6-step order

Goal:

$A1 \rightarrow B1 \rightarrow A2 \rightarrow B2 \rightarrow A3 \rightarrow B3$.^[1]

Use three semaphores, all initialized to 0:

- start1 controls B1 after A1.
- start2 controls A2 after B1.
- start3 controls B2 after A2.
- start4 controls A3 after B2.
- start5 controls B3 after A3.

All are semaphores; initial values: start1 = start2 = start3 = start4 = start5 = 0.

Process A	Process B
A1;	P(start1);
V(start1); // allow B1	B1;
P(start2); // wait for B1	V(start2); // allow A2
A2;	P(start3);
V(start3); // allow B2	B2;
P(start4); // wait for B2	V(start4); // allow A3
A3;	P(start5);
V(start5); // allow B3	B3;

This guarantees the strict global order

$A1$ (then signal) $\rightarrow B1 \rightarrow A2 \rightarrow B2 \rightarrow A3 \rightarrow B3$, using only simple binary semaphores and the same pseudocode style.