

CHAPTER 2

LINEAR APPLICATIONS

2.1 Definition of a Linear Application

2.2 Kernel and Image of a Linear Application

2.3 Rank Theorem

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2.1 Definition of a Linear Application

- **Definition:**

A linear application $f: E \rightarrow F$ between two vector spaces E and F is a function that preserves vector addition and scalar multiplication. Specifically, for all $u, v \in E$ and $\alpha \in R$, the following properties are satisfied:

$$f(u + v) = f(u) + f(v) \quad (\text{Additivity})$$

$$f(\alpha u) = \alpha f(u) \quad (\text{Homogeneity})$$

Examples:

□ $f: R^2 \rightarrow R^2$ defined by $f(x, y) = (2x, 3y)$, f is linear.

□ $g: P_n(R) \rightarrow P_{n-1}(R)$ where g is the differentiation operator $g(p(x)) = p'(x)$ g is linear.

□ $h: R^2 \rightarrow R^2$ defined by $h(x, y) = x^2 - y^2$, h is not linear.

2.2 Kernel and Image of a Linear Application

► **Kernel (Ker):**

The kernel of f is the set of vectors in E that are mapped to the zero vector in F .

$$\text{Ker}(f) = \{v \in V \mid f(v) = 0\}$$

Examples:

(1) For $f(x,y) = (2x, 3y)$, $\text{Ker}(f) = \{(0, 0)\}$.

(2) For the differentiation operator $f(p(x)) = p'(x)$, determine the kernel.

2.2 Kernel and Image of a Linear Application

► **Image (Im):**

The image of f is the set of vectors in F that are obtained as images of vectors from E .

$$\text{Im}(f) = \{f(v) / v \in V\}$$

Examples:

(1) For $f(x,y) = (2x, 3y)$, $\text{Im}(f) = \mathbb{R}^2$.

(2) For the differentiation operator $f(p(x)) = p'(x)$, determine the Image.

2.3 Rank Theorem

► **Statement:**

For a linear application $f:E\rightarrow F$, the dimension of E is equal to the sum of the dimension of the kernel of f and the dimension of the image of f :

$$\dim(E) = \dim(\text{Ker}(f)) + \dim(\text{Im}(f))$$

■ **Interpretation:**

This theorem connects the internal structure of E to how f acts on E .

Examples:

Apply the rank theorem to specific cases, such as $f:R^3\rightarrow R^2$.